Enhancing Dual-task Learning through Supraposture-first Instruction in Healthy Young Adults

Shu-Han Yu1 and Cheng-Ya Huang1,2*
1School and Graduate Institute of Physical Therapy, College of Medicine, National Taiwan University, Taipei, Taiwan
2Physical Therapy Center, National Taiwan University Hospital, Taipei, Taiwan

Abstract

Background: Previous studies have demonstrated that the performance of a postural-suprapostural dual task can be modulated by varied attention prioritization. The purpose of this study was to compare the effects of two task-priority approaches to dual-task learning on accuracy and dynamic characteristics of postural-suprapostural performance.

Methods: We concurrently conducted a force-matching precision grip task (suprapostural task) while maintaining a stabilometer stance (postural task). Twenty adults were randomly assigned to one of two learning conditions: (1) dual-task learning with prioritizing force-matching precision grip task (supraposture first, SF), or (2) dual-task learning with prioritizing stabilometer movement (posture first, PF). Force-matching error, postural error, and dynamics of force-matching peak and stabilometer movement were evaluated.

Results: Dual-task learning with the SF strategy caused superior force-matching, postural accuracy, and more complex stabilometer movements than dual-task learning with the PF strategy.

Conclusion: Dual-task learning with the SF strategy takes advantage of more autonomous and flexible postural responses to facilitate the suprapostural performance.

Introduction

Dual-task paradigms have been widely used to evaluate the extent of information-processing sharing requirement of postural tasks with other concurrent tasks. Traditionally, upright posture control is assumed to be an automatic task without higher-level cortical processing, as large-scale stance synergies are well established. In daily life, many activities involve maintaining balance while performing at least one other concurrent task (e.g. walking and texting). The task which is superordinate to the postural control is the suprapostural task [1]. The influence of adding a suprapostural task on balance control has received considerable attention. Growing literature on the performance of postural control functions has shown that maintaining upright balance is a complex physical task, especially while carrying out a suprapostural task [2,3]. Task prioritization is often manipulated to better understand the role of attention in postural-suprapostural control. The simultaneous performance of a postural task and a suprapostural task may create a conflict, causing the need to determine which of the tasks receives higher priority, especially when attentional resources to execute both task concurrently are limited [4]. However, much of the literature on dual-tasking has participants performing a postural task and a suprapostural task simultaneously without specific instructions about task prioritization.

While performing a dual-task, the tasks must be appropriately prioritized to achieve goals while maintaining safety. The “posture-first” concept, originally introduced by Shumway-Cook et al. in 1997, is considered a safe strategy, favoring balance maintenance over execution of a suprapostural task. Some studies reported that healthy young adults are more inclined to use this posture first strategy to prevent fall [5,6]. Bloem et al. (2001, 2006) even proposed that Parkinson patients who easily fall because they prioritize a “posture-second” (or “supraposture-first”) strategy in daily life [7,8]. However, some other dual-task studies reported that healthy young adults might better perform by using the supraposture-first strategy instead of posture first strategy. Healthy young adults were asked to walk on a narrow-base while executing an auditory Stroop test [9]. Focusing on the Stroop test caused a faster response to the Stroop test and did not decrease walking speed. However, when the subjects focused on the walking task, their response time and accuracy for the Stroop test deteriorated significantly. Similarly, while standing on a platform with feet together and performing a visual spatial memory task, focusing on the memory task caused a shorter response time and did not increase postural sway relative to focusing on the postural balance [10]. This phenomenon implies that posture-first is not an invariant strategy and that attention prioritization is flexible, depending on various individual tasks, and environmental factors [9,11].

Few studies have addressed the impact of dual-task learning with variable attention prioritization. The benefit of dual-task learning with switching attention between postural and suprapostural tasks was shown by Silsupadol et al. [12,13] with the variable-priority strategy and participants were asked to shift attention between postural and suprapostural tasks by focusing on balance activities (posture-first) in half the learning session and focusing on cognitive tasks (supraposture-first) in the other half. Both the learning effect and the transfer effect had better outcomes relative to when the participants placed the same amount of attention on balance activities and cognitive tasks (equal priority) during the whole training session. However, to our knowledge, no research has been done examining the effects of various attention prioritization (posture-first vs. supraposture-first) on dual-task learning. By adopting posture-first and supraposture-first strategies for dual-task learning, the main purpose of the present study was to assess which attention prioritization

Corresponding Author: Dr. Cheng-Ya Huang, School and Graduate Institute of Physical Therapy, College of Medicine, National Taiwan University, Taipei, 100, Taiwan, Tel: 886-2-33688131; E-mail: rcyhuanggg@ntu.edu.tw

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strategy (posture-first or supraposture-first) optimizes postural-suprapostural dual-tasking learning. We hypothesized that dual-task learning would change postural and suprapostural performance in relation to the attention prioritization of the dual-task condition.

Method

Subjects

The study was conducted with 20 healthy right-handed participants (8 male, 12 female; mean age: 24.5 ± 3.3 years) from the university campus. All participants signed an informed consent for the experimental procedure, approved by the local institutional review board (National Taiwan University Hospital Clinical Trail Center) to protect the rights of the subjects. Participants who were not able to maintain their balance on a stabilometer (58-cm length × 50-cm width × 26-cm height) for at least 80 seconds, had history of a neuromuscular system disease, or any injury that could affect their balance, were excluded from this study.

Experimental procedures and system-setup

The participants were asked to perform a force-matching precision grip task with their right index and thumb while standing on a stabilometer in the postural-suprapostural dual-task condition (Figure 1). For the postural task, participants were asked to maintain their balance on the stabilometer with an inclinometer (Model: FAS-A, MicroStrain, USA) mounted on the center of the stabilometer plate to measure the tilting angle of the stabilometer. The maximal anterior tilting angle was recorded before the experiment and 50% of the maximal anterior tilting angle was set as the target angle for the postural task. For the suprapostural task, participants executed a thumb-index precision grip task, and the level of force output was recorded with a load cell (15-mm diameter × 10-mm thickness, net weight = 7 grams; Model: LCS, Nippon Tokushu Sokki Co., Japan). Maximum voluntary contraction (MVC) of the precision grip was recorded before the experiment and 50% of the MVC was set as the target force of the suprapostural task. The participants needed to execute the thumb-index precision grip task in response to auditory cues. The auditory cues consisted of 80-second sequences of tone pips, with a total of fifteen warning-executive signal pairs. The interval between a warning tone (frequency: 800 Hz, duration: 100 ms) and an executive tone (frequency: 500 Hz, duration: 100 ms) was 1.5 seconds for the first three warning-executive pairs, but was randomly presented at different intervals of 1.5, 1.8, 2.1, 2.4, 2.7 or 3.0 seconds from the fourth to fifteenth warning-executive pairs. The interval between the executive tone and the next warning tone was 3.5 seconds. Participants performed a quick thumb-index precision grip (force impulse duration < 0.5 second) to couple the peak precision force with the force target when receiving the executive tone.

Participants were randomly assigned to either the posture-first group (PF group; 10 subjects) or the supraposture-first group (SF group; 10 subjects). Because the major limitation in most of the previous studies related to attention prioritization is the lack of specific instructions regarding to how the participants should direct their attention when performing dual tasks [14], we used a procedure derived from the “optimum-maximum method” proposed by Navon [15] to manipulate task priority in this study. The optimum-maximum method was used to guard the subjects’ attention with specific instruction for both high-priority and low-priority tasks [16,17]. With this method, the high-priority task was designed as the “to-be-optimized” task, and the low-priority task was the “to-be-maximized” task. Participants were instructed to maintain an optimum performance level on the high-priority task and to perform their best on the low-priority task. Such a procedure requires participants to optimize the high-priority task and to not give up on the low-priority task. In addition, individually determined performance standard and feedback were provided in the to-be-optimized task but not for to-be-maximized task. In this study, visual feedback about the target and performance of stabilometer movement and force-matching was used to enhance the attention priority. For example, participants in the PF group were instructed to concentrate more on the postural task, maintaining the tilting angle of the stabilometer at the target angle precisely and to maximize the precision of force-matching. Visual feedback of the stabilometer target angle and instantaneous stabilometer tilting angle were provided in the PF group, but visual information about the force target and force-output was not. In contrast, participants in the SF group were instructed to concentrate more on the precision grip task with coupling the force peak with the target precisely, and to maximize the precise tilting angle of the stabilometer. Visual feedback of force target and force-output of the load cell were provided in the SF group, but visual information about the stabilometer movement and its target angle was not. In addition, visual feedback for the target force for the PF group and the target tilting angle for the SF group were provided.
as reminders. In each trial, we provided the visual feedback for the first three force-matching performances and the first 10 second-stabilometer tilting angle with their targets for the PF group and the SF group respectively. All the visual feedback was presented on a 22-inch computer monitor 60 cm in front of subjects at eye-level. Besides the dual-task, the subjects needed to performed the corresponding single task condition for both postural and suprapostural tasks. units were converted to degrees. To assess the performance of the postural tasks and suprapostural tasks, we calculated the error and variance of both tasks.

Data recording

This study was conducted over a period of three successive days. The first day and the third day were pre-learning and post-learning phases respectively and the second day was the learning phase. There were five trials for the three experimental conditions (The dual-task task and its corresponding single posture and single force-matching precision grip conditions) in both pre-learning and post-learning tests. In the learning phase, participants performed the postural-suprapostural dual-task for 10 trials with assigned task priority. A one-minute break was given after every trial to minimize fatigue. Both inclinometer and load cell data were digitized at a sample rate of 1 kHz.

Data analyses

The inclinometer data were conditioned with 6-Hz low-pass filter and the units were converted to degrees. To assess the performance of the postural tasks and suprapostural tasks, we calculated the error and variance of both tasks. Postural error was presented by calculating the root mean square of the mismatch between the target angle and the stabilometer tilting angle. The approximate entropy (ApEn) of the stabilometer tilting angle's trajectory was used to represent the variability property of the postural task. The value of the ApEn is between 0 and 2, with a value of closer to 2 representing higher irregularities, or larger complexity of the postural movement changes [18]. The force-matching error was presented as \( \frac{PGF - TF}{TF} \times 100\% \) (PGF: peak precision grip force, TF: target force), and the coefficient of variation (CV) of the peak precision grips was used to represent the variability property of the force control. To assess the effect on postural and suprapostural performance when executing postural-suprapostural dual-tasks with a different task priority, the dual-task effect (DTE) [19] was calculated for each parameter. We calculated the DTE values for the task errors, CV of peak precision-grip force and ApEn of stabilometer movement as follows:

\[
DTE(\%) = \frac{[(\text{dual-task performance} - \text{single-task performance})]/\text{single-task performance}] \times 100
\]

Positive DTE values indicate an increase in task error or task variance under dual-task conditions compared to single-task condition, representing more dual-task cost. In contrast, negative DTE values represent the dual-task benefit. The attention prioritization (PF, SF) and learning (pre-learning, post-learning) effects on posture and supaposture parameters, including the DTE values of postural error, force error, postural ApEn, and force CV, were compared with repeated-measures analysis of variance (ANOVA). When necessary, post hoc least significant difference (LSD) comparisons were performed. The level of significance was set at \( p = 0.05 \). Signal processing of behavioral data and statistical analysis were completed by using Matlab v. R2012a (Mathworks, Natick, MA, USA) and the statistical package for SPSS statistics v. 17.0 (SPSS Inc., Chicago, IL, USA).

Results

Suprapostural task performance

Figure 2 shows the DTE values of force error and force CV which represents the force-matching precision and variability for PF and SF groups during pre-learning and post-learning phases. For the force-matching error, significant attention prioritization \( (F_{1,9} = 1.38; p < .01) \) and learning \( (F_{1,9} = 16.92; p < .01) \) effects were observed. Post-hoc evaluation further revealed that the force-matching error was reduced after learning \( (p < .05) \) for both PF and SF groups (Figure 1, left). However, force-matching errors were greater in the PF group during pre-learning and post-learning phases than those in the SF group \( (p < .05) \). We found a negative DTE values for the force-matching error \((-11.11 \pm 4.23\%) \) of the SF group during the post-learning phase. This indicated that force-matching precision was better in the dual-task condition than that in the single force-matching condition while subjects focused on the precision grip task during dual-task learning. For the DTE values of force CV (Figure 2, right), both the PF and SF groups decreased the variability property of force control after learning \( \text{SF: pre-learning} = 12.44 \pm 4.98\%, \text{post-learning} = -5.21 \pm 4.66\%, p < .05; \text{PF: pre-learning} = 15.23 \pm 6.02\%, \text{post-learning} = -6.47 \pm 4.94\%, p < .05) \), but no significant difference was found between the two groups.

Postural task performance

Figure 3 displays the means and standard error of DTE values of force-matching error and force CV between the PF and SF groups during pre-learning and post-learning tests. (PF: posture-first; SF: supraposture-first; Pre: pre-learning test; Post: post-learning test).

\[ DTE = \frac{[(\text{dual-task performance} - \text{single-task performance})]/\text{single-task performance}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task error} - \text{single-task error})]/\text{single-task error}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task CV} - \text{single-task CV})]/\text{single-task CV}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task variance} - \text{single-task variance})]/\text{single-task variance}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task variability} - \text{single-task variability})]/\text{single-task variability}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task precision} - \text{single-task precision})]/\text{single-task precision}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task efficiency} - \text{single-task efficiency})]/\text{single-task efficiency}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task variability} - \text{single-task variability})]/\text{single-task variability}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task precision} - \text{single-task precision})]/\text{single-task precision}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task efficiency} - \text{single-task efficiency})]/\text{single-task efficiency}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task variability} - \text{single-task variability})]/\text{single-task variability}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task precision} - \text{single-task precision})]/\text{single-task precision}] \times 100 \]

\[ \text{DTE} = \frac{[(\text{dual-task efficiency} - \text{single-task efficiency})]/\text{single-task efficiency}] \times 100 \]
The ANOVA results showed that there was no priority and learning effects on postural ApEn, but showed a significant interaction between task priority and learning effect ($F_{1,9} = 14.20; p < 0.01$). A post-hoc analysis revealed that the SF group had a lower DTE value of postural ApEn relative to the PF group before training ($p < 0.05$) (Figure 2, right). However, after learning, postural ApEn decreased in the PF group (pre-learning: 10.02 ± 4.98; post-learning: -2.34 ± 2.84, $p < 0.05$) but increased in the SF group (pre-learning: -5.39 ± 2.86%, post-learning: 3.80 ± 2.81 %, $p < 0.05$) indicating postural variance varied depending on different attention prioritization strategy.

Discussion

A decrease in postural accuracy with posture-first learning

This study provides evidence that a dual-task learning program with supraposture-first strategy is effective in improving postural and suprapostural accuracy. After the 1-day intervention, participants in the SF group significantly improved performance on both force-matching and postural tasks. Even though the PF and SF groups were equally effective at improving force-matching performance, including reducing the DTE values of force-matching error and variability, the SF group was superior to the PF group in force-matching accuracy in both pre-learning and post-learning phases. The results are in line with previous studies [9,19]. During walking or narrow standing while performing an auditory cognitive task, the reaction time of the cognitive task was much shorter when focusing on the cognitive task than when focusing on posture. In addition, we found that the SF group reversed the DTE value of force-matching from positive to negative after learning. This finding suggests that with the supraposture-first strategy, the phenomenon of "dual-task cost" transfers to "dual-task benefit" for suprapostural performance even with a very short learning session.

Surprisingly, we found that dual-task learning with the posture-first strategy degraded postural accuracy. However, with the supraposture-first strategy, postural accuracy improved. This result is in agreement with a study showing increased dual-task cost of postural accuracy while focusing on postural task when performing a stepping task (posture task) and an auditory Stroop task simultaneously [20].

Our results support the constrained action hypotheses which states that improvements in postural control should be apparent when prioritizing attention away from the posture itself, suggesting that increasing the level of controlled processing of posture will increase postural instability in young adults [21]. Furthermore, recent studies have demonstrated functional adjustments of postural sway in response to suprapostural task goals. For instance, postural sway was found to be reduced when the more attention was required for suprapostural tasks [22,23]. Thus, the motor system seems to be able to automatically adjust posture to the demands of other required tasks.

An increase in postural irregularity with supraposture-first learning

One of the important findings in this study is that dual-task learning by focusing on the force-matching task decreased postural regularity with increased postural ApEn. In contrast, learning by focusing on the stabiometer movement increased postural regularity with decreased postural ApEn (Figure 3). The ApEn has been used to characterize stochastic features of postural performance while standing on a force plate or on a stabiometer [24-26]. A more regular CoP signal or stabiometer movement is associated with increased attentional investments in postural control, reflecting less automaticity or postural control. For pathological groups such as patients with stroke or ligament laxity, postural sway is more regular (low value of ApEn) than for healthy controls during quiet standing [24,25]. According to Roerdink et al., CoP trajectories are more regular in stroke patients than in controls and become less regular when performing a secondary cognitive task while standing [24]. This suggests that the measure of complexity or irregularity of a system is linked to efficiency or automaticity of postural control. All activities that are over-learned would execute automatically using minimum attentional resources and do not stress the capacity limitations of the system or demand excessive attention [27]. According to our ApEn results, participants who learned the dual task using prioritizing posture concentrated more on postural task and interrupted the automatized postural control, resulting in greater postural errors. Moreover, increased postural regularity in the PF group may have been caused by participants adopting a more rigid posture with a posture-first strategy [11]. These findings also provide support for the idea that focusing attention away from posture allows for "functional variability" [28], such that the motor system automatically adjusts the various degrees of freedom to achieve postural balance and facilitate force-matching control.

Study Limitations

Our results provide little support for a theoretical position that frames the attention prioritization interaction between postural and suprapostural control. Rather, this study supports the proposition that the supraposture-first strategy is more efficient for dual-task learning in young adults than the posture-first strategy. However, it is conceivable that the dual-tasking effects are modulated by individual differences in attentional capacity. With increasing age, the efficacy of sensory and muscular systems involved in postural control are reduced resulting in more limited attentional capacity for performing dual tasks [29]. Indeed, lack of flexibility when focusing attention between postural and suprapostural tasks was observed in older adults [30]. Therefore, the supraposture-first strategy may not be the most appropriate action strategy in dual-task learning for older adults who cannot manage the attentional cost of both tasks. Future studies are needed to identify the attention prioritization effects on dual-task training in older adults for achieving optimized dual-task learning.
training dual-task performances in healthy young and older people in automatic processing of postural control. These findings may help in first instruction may not benefit postural balance due to disturbing postural-suprapostural control. Dual-task learning under posture-accuracy, and increase functional variability of posture to optimize supraposture-first strategy can enhance suprapostural and postural task performances. More specifically, dual-task learning with

11. References
